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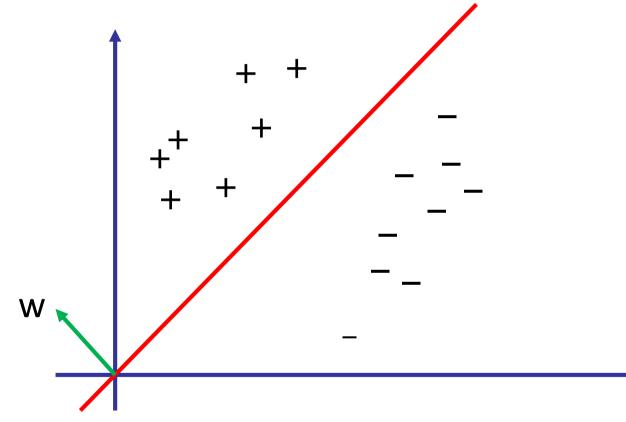


Introduction to Machine Learning

Non-linear prediction with kernels

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Recall: Linear classifiers



$$\hat{y} = \operatorname{sign}(\mathbf{w}^T \mathbf{x})$$

Recall: The Perceptron problem

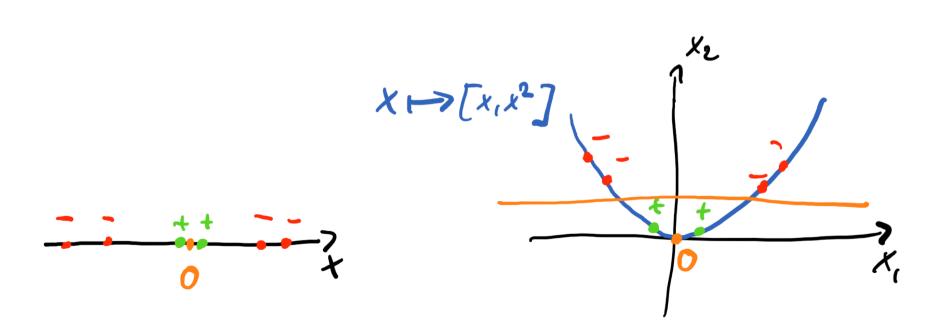
• Solve
$$\hat{\mathbf{w}} = \arg\min_{\mathbf{w}} \frac{1}{n} \sum_{i=1}^{n} \ell_P(\mathbf{w}; \mathbf{x}_i, y_i)$$

where
$$\ell_P(\mathbf{w}; y_i, \mathbf{x}_i) = \max(0, -y_i \mathbf{w}^T \mathbf{x}_i)$$

Optimize via Stochastic Gradient Descent

Solving non-linear classification tasks

- How can we find nonlinear classification boundaries?
- Similar as in regression, can use non-linear transformations of the feature vectors, followed by linear classification



 $x_1 = x_1 x_2 = x^2$

Recall: linear regression for polynomials

 We can fit non-linear functions via linear regression, using nonlinear features of our data (basis functions)

$$f(\mathbf{x}) = \sum_{i=1}^{d} w_i \phi_i(\mathbf{x})$$

For example: polynomials (in 1-D)

$$f(x) = \sum_{i=0}^{m} w_i x^i$$

Polynomials in higher dimensions

- Suppose we wish to use polynomial features, but our input is higher-dimensional
- Can still use monomial features
- **Example**: Monomials in 2 variables, degree = 2

$$X = \begin{bmatrix} X_1, X_2 \end{bmatrix} \qquad \longmapsto \qquad \bigoplus \begin{pmatrix} x \end{pmatrix} = \begin{bmatrix} X_1^2, X_2^2, X_1 \cdot X_2 \end{bmatrix}$$

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Avoiding the feature explosion

- Need O(d^k) dimensions to represent (multivariate) polynomials of degree k on d features
- **Example**: d=10000, $k=2 \rightarrow$ Need ~100M dimensions
- In the following, we can see how we can efficiently implicitly operate in such high-dimensional feature spaces (i.e., without ever explicitly computing the transformation)

Revisiting the Perceptron/SVM

- Fundamental insight: Optimal hyperplane lies in the span of the data $\hat{\mathbf{w}} = \sum_{i=1}^{n} \alpha_i y_i \mathbf{x}_i$
- (Handwavy) proof: (Stochastic) gradient descent starting from 0 constructs such a representation

Perceptron: $\mathbf{w}_{t+1} = \mathbf{w}_t + \eta_t y_t \mathbf{x}_t [y_t \mathbf{w}_t^T \mathbf{x}_t < 0]$

SVM: $\mathbf{w}_{t+1} = \mathbf{w}_t (1 - 2\lambda\eta_t) + \eta_t y_t \mathbf{x}_t [y_t \mathbf{w}_t^T \mathbf{x}_t < 1]$

 More abstract proof: Follows from the "representer theorem" (not discussed here)

Reformulating the Perceptron

(42)
$$\hat{W} \in \operatorname{atomin}_{i=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{1} - y_{i} \\ v_{i} \end{array} \right)^{T} \xrightarrow{i=1}_{i=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{1} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{i=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{1} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{1} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{1} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \vdots \end{array} \right)^{T} \xrightarrow{i=1}_{j=1}^{n} \operatorname{max} \left(\begin{array}{c} 0_{i} - y_{i} \\ \end{array} \right)$$

Advantage of reformulation

$$\hat{\alpha} = \arg\min_{\alpha_{1:n}} \frac{1}{n} \sum_{i=1}^{n} \max\{0, -\sum_{j=1}^{n} \alpha_j y_i y_j \underbrace{\mathbf{x}_i^T \mathbf{x}_j}_{\substack{\forall \\ \notin (\mathbf{x}_i \mid \mathbf{x}_j)}}\}$$

- Key observation: Objective only depends on inner products of pairs of data points
- Thus, we can implicitly work in high-dimensional spaces, as long as we can do inner products efficiently

$$\mathbf{x} \mapsto \phi(\mathbf{x})$$
$$\mathbf{x}^T \mathbf{x}' \mapsto \phi(\mathbf{x})^T \phi(\mathbf{x}') =: k(\mathbf{x}, \mathbf{x}')$$

"Kernels = *efficient* inner products"

- Often, $k(\mathbf{x}, \mathbf{x'})$ can be computed much more efficiently than $\phi(\mathbf{x})^T \phi(\mathbf{x'})$
- Simple example: Polynomial kernel in degree 2

$$\begin{array}{l} \mathcal{X} \longmapsto \Phi(x) := \left[\chi_{i}^{2}, \chi_{2}^{2}, \sqrt{2}, \chi_{i}\chi_{2} \right] & (2+0) \gg (1+3) \\ \in \mathbb{N}^{2} & \Pi \\ \Phi(x)^{T} \Phi(x^{1}) = \chi_{i}^{2}, \chi_{i}^{12} + \chi_{2}^{2}, \chi_{2}^{12} + 2\chi_{i}\chi_{2}, \chi_{i}\chi_{2} \right] & \begin{array}{l} \text{Maire:} \\ \text{Maire:} \\ \Phi(x)^{T} \Phi(x^{1}) = \chi_{i}^{2}, \chi_{i}^{12} + \chi_{2}^{2}, \chi_{2}^{12} + 2\chi_{i}\chi_{2}, \chi_{i}\chi_{2} \right] & \begin{array}{l} \text{Maire:} \\ \Psi(x)^{T} \Phi(x) \\ \Psi(x)^{T} \Phi(x) \\ = \left(\chi_{i}, \chi_{i}^{1} + \chi_{2}\chi_{2}^{1} \right)^{2} \\ = \left(\chi^{T} \chi^{1} \right)^{2} = b \left(\chi_{i}\chi^{1} \right) & \begin{array}{l} \text{Maire:} \\ \Psi(x)^{T} \Phi(x) \\ \Psi(x)^{T} \Psi(x) \\ \Psi(x)^{T}$$

• Suppose
$$\mathbf{x} = [x_1, \dots, x_d]^T$$
 and $\mathbf{x}' = [x'_1, \dots, x'_d]^T$
• Then $(\mathbf{x}^T \mathbf{x}')^2 = \left(\sum_{i=1}^d x_i x'_i\right)^2 = \bigcup_{i=1}^d x'_i x'_i^2 + 2 \bigcup_{i \in i \in j \notin j} x'_i x'_i x'_j x'_j^2$

$$= \Phi(x)^{T} \Phi(x')$$
for $\Phi(x) := [x_{1}^{2} - x_{d_{1}}^{2} \sqrt{2} x_{1} x_{d_{1}} \sqrt{2} x_{1} x_{d_{1}} \sqrt{2} x_{1} x_{d_{1}} \sqrt{2} x_{1} x_{d_{1}} \sqrt{2} x_{d_{1}} x_{d_{1}} \sqrt{2} x_{d_{1}} \sqrt{$

Polynomial kernels: Fixed degree

• The kernel $k(\mathbf{x}, \mathbf{x}') = (\mathbf{x}^T \mathbf{x}')^m$ implicitly represents all monomials of degree *m*

Monomials of degree
$$m$$
 in d variables
 $\left(d + m - 1 \right) = O(d^{m})$

How can we get monomials up to order m?

Polynomial kernels ([[[,x]])"

• The polynomial kernel $k(\mathbf{x}, \mathbf{x}') = (1 + \mathbf{x}^T \mathbf{x}')^m$ implicitly represents all monomials of up to degree *m*

Monomials of degree up to m in d variables?

$$\int (d+m) d(m)$$

 Representing the monomials (and computing inner product explicitly) is *exponential* in *m*!!

The "Kernel Trick"

- Express problem s.t. it only depends on inner products
- Replace inner products by kernels

$$\mathbf{x}_i^T \mathbf{x}_j \quad \triangleright \quad k(\mathbf{x}_i, \mathbf{x}_j)$$

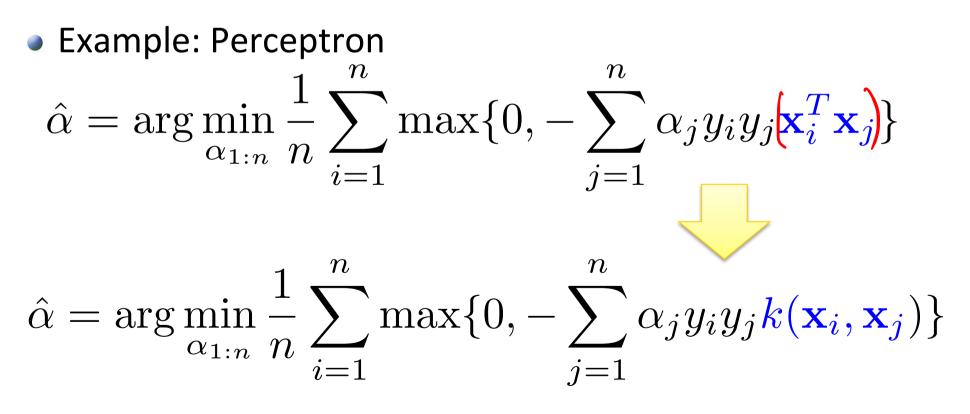
This "trick" is very widely applicable!

The "Kernel Trick"

- Express problem s.t. it only depends on inner products
- Replace inner products by kernels
- Example: Perceptron

The "Kernel Trick"

- Express problem s.t. it only depends on inner products
 Replace inner products by kernels



Will see further examples later

Derivation: Kernelized Perceptron

 $W_{t} = \sum_{i=1}^{d} t_{ii} y_{i} k_{j}$ Training $d \in O$ $w_{a} \in O$ for f=1For += (,?,... Sample (Kicy;)~) Sample $(X_i, y_i) \sim D$ if (y; £12; y(k; [x.]))20 If $(y_i \, \sqrt{x_i}) > 0$ $e(x, x_{t})$ $\mathcal{W}_{++1} \leftarrow \mathcal{W}_{+}$ dt+1 E dt else l(se $W_{t+1} \in W_t + \mathcal{N}_t \mathcal{Y}_i \mathcal{K}_i$ $d_{t+i} \in d_t$ Presidenti duice dui + 1/4 18

Kernelized Perceptron

• Initialize $\alpha_1 = \cdots = \alpha_n = 0$

Training

For *t=1,2,...*Pick data point (*x_i, y_i*) uniformly at random

For

• Predict $\hat{y} = \operatorname{sign}\left(\sum_{i=1}^{n} \alpha_{j} y_{j} k(\mathbf{x}_{j}, \mathbf{x}_{i})\right)$

• If
$$\hat{y} \neq y_i$$
 set $\alpha_i \leftarrow \alpha_i + \eta_t$

Prediction

new point x, predict

$$\hat{y} = \operatorname{sign}\left(\sum_{j=1}^{n} \alpha_j y_j k(\mathbf{x}_j, \mathbf{x})\right)$$

Demo: Kernelized Perceptron

Questions

- What are valid kernels?
- How can we select a good kernel for our problem?
- Can we use kernels beyond the perceptron?
- Kernels work in very high-dimensional spaces.
 Doesn't this lead to overfitting?

Properties of kernel functions

- Data space X
- A kernel is a function $k: X \times X \to \mathbb{R}$
- Can we use any function?
- *k* must be an inner product in a suitable space
- → *k* must be symmetric!

 $\forall x, x' \in X: \quad b(x, x') = \phi(x)^T \phi(x') = \phi(x')^T \phi(x) = b(x', x)$

→ Are there other properties that it must satisfy?

Positive semi-definite matrices

Symmetric matrix $M \in \mathbb{R}^{n \times n}$ is positive semidefinite iff (i) $\forall x \in \mathbb{R}^{n}$: $x \stackrel{\mathsf{T}}{} M x 20$ \equiv (ii) All eigenvalues of M 20

 $(i) \Rightarrow (ii): M \text{ is symmetric} \Rightarrow M = UDUT \text{ for } D = \begin{pmatrix} \lambda_i & 0 \\ 0 & \ddots \end{pmatrix}$ $U = \begin{pmatrix} u_i & | - u_i \end{pmatrix} \text{ s.t. } M_{u_i} = \lambda_{u_i}$ $U = \begin{pmatrix} u_i & | - u_i \end{pmatrix} \text{ s.t. } M_{u_i} = \lambda_{u_i}$ $U = \begin{pmatrix} u_i & | - u_i \end{pmatrix} \text{ s.t. } M_{u_i} = \lambda_{u_i}$ $U = \begin{pmatrix} u_i & | - u_i \end{pmatrix} \text{ s.t. } M_{u_i} = \lambda_{u_i}$ $U = \begin{pmatrix} u_i & | - u_i \end{pmatrix} \text{ s.t. } M_{u_i} = \lambda_{u_i}$ $U = \begin{pmatrix} u_i & | - u_i \end{pmatrix} \text{ s.t. } M_{u_i} = \lambda_{u_i}$ $U = \begin{pmatrix} u_i & | - u_i \end{pmatrix} \text{ s.t. } M_{u_i} = \lambda_{u_i} \text{ s.t. } M_{u_i} = \lambda_{u_i}$ $U = \begin{pmatrix} u_i & | - u_i \end{pmatrix} \text{ s.t. } M_{u_i} = \lambda_{u_i} \text{ s.$

- Data space X (possibly infinite)
- Kernel function $k: X \times X \to \mathbb{R}$
- Take any finite subset of data $S = {\mathbf{x}_1, \dots, \mathbf{x}_n} \subseteq X$
- Then the kernel (gram) matrix

$$\mathbf{K} = \begin{pmatrix} k(\mathbf{x}_1, \mathbf{x}_1) & \dots & k(\mathbf{x}_1, \mathbf{x}_n) \\ \vdots & & \vdots \\ k(\mathbf{x}_n, \mathbf{x}_1) & \dots & k(\mathbf{x}_n, \mathbf{x}_n) \end{pmatrix} = \begin{pmatrix} \phi(\mathbf{x}_1)^T \phi(\mathbf{x}_1) & \dots & \phi(\mathbf{x}_1)^T \phi(\mathbf{x}_n) \\ \vdots & & \vdots \\ \phi(\mathbf{x}_n)^T \phi(\mathbf{x}_1) & \dots & \phi(\mathbf{x}_n)^T \phi(\mathbf{x}_n) \end{pmatrix}$$

^

is positive semidefinite

$$K = \Phi^T \Phi \quad \text{where} \quad \Phi = \left(\Phi(X_i) \left| \dots \left| \Phi(X_n) \right| \right)$$

Sps: $x \in TR^n$: $x^T K K = \left(x^T \Phi^T \Phi X \right) = v^T v \ge 0$
 $v^T v$

- Suppose the data space $X = \{1, ..., n\}$ is finite, and we are given a positive semidefinite matrix $\mathbf{K} \in \mathbb{R}^{n \times n}$
- Then we can always construct a feature map

$$\phi: X \to \mathbb{R}^{n}$$
such that $\mathbf{K}_{i,j} = \phi(i)^{T} \phi(j)$
 $\& \text{ is s.p.d.} \Rightarrow \& = U D U^{T} \text{ More } D = \begin{pmatrix} \lambda_{i} & 0 \\ 0 & \lambda_{n} \end{pmatrix} \quad \phi: X \to \mathbb{R}^{n}$
 $\text{od } \lambda_{i} \geq 0 \quad \forall i$
 $D = D^{\frac{1}{2}} D^{\frac{1}{2}T} \text{, where } D^{\frac{1}{2}} = \begin{pmatrix} \nabla \lambda_{i} & 0 \\ 0 & \lambda_{n} \end{pmatrix} \quad \phi: X \to \mathbb{R}^{n}$
 $\Rightarrow \& = U D^{\frac{1}{2}} D^{\frac{1}{2}T} \text{, where } D^{\frac{1}{2}} = \begin{pmatrix} \nabla \lambda_{i} & 0 \\ 0 & \sqrt{\lambda_{n}} \end{pmatrix} \quad \phi: i \mapsto \phi_{i}$
 $\Rightarrow \& u = U D^{\frac{1}{2}} D^{\frac{1}{2}} U^{T} = \phi^{T} \phi \text{, where } \phi = [\phi_{i}[\dots]_{n}]$
 $N_{ow} \text{ it holds that } b(i = 0; i) = \&_{i,j} = \phi_{i}^{T} \phi_{j}$

Outlook: Mercer's Theorem

Let X be a compact subset of \mathbb{R}^n and $k: X \times X \to \mathbb{R}^n$ a kernel function

Then one can expand k in a uniformly convergent series of bounded functions ϕ_i s.t.

$$k(x, x') = \sum_{i=1}^{\infty} \lambda_i \phi_i(x)\phi_i(x')$$

Can be generalized even further

Definition: kernel functions

- Data space X
- A kernel is a function $k: X \times X \to \mathbb{R}$ satisfying
- 1) Symmetry: For any $\mathbf{x}, \mathbf{x}' \in X$ it must hold that $k(\mathbf{x}, \mathbf{x}') = k(\mathbf{x}', \mathbf{x})$
- 2) Positive semi-definiteness: For any *n*, any set $S = \{\mathbf{x}_1, \dots, \mathbf{x}_n\} \subseteq X, \text{ the kernel (Gram) matrix}$ $\mathbf{K} = \begin{pmatrix} k(\mathbf{x}_1, \mathbf{x}_1) & \dots & k(\mathbf{x}_1, \mathbf{x}_n) \\ \vdots & & \vdots \\ k(\mathbf{x}_n, \mathbf{x}_1) & \dots & k(\mathbf{x}_n, \mathbf{x}_n) \end{pmatrix}$

must be positive semi-definite

Examples of kernels on \mathbb{R}^d

- Linear kernel:
- Polynomial kernel:

$$k(\mathbf{x}, \mathbf{x}') = \mathbf{x}^T \mathbf{x}'$$
$$k(\mathbf{x}, \mathbf{x}') = (\mathbf{x}^T \mathbf{x}' + 1)^d$$

 Gaussian (RBF, $k(\mathbf{x}, \mathbf{x}') = \exp(-||\mathbf{x} - \mathbf{x}'||_2^2/h^2)$ squared exp. kernel): $\Lambda (e(\lambda_{\ell} \kappa^{\ell}))$ "Bondwidth"/ Longth scale parameter $k(\mathbf{x}, \mathbf{x}') = \exp(-||\mathbf{x} - \mathbf{x}'||_1/h)$ Laplacian kernel: n b (K, K'S