Homework 6 & Mixture models

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Let $D = \{(\mathbf{x}^{(1)}, y^{(1)}), \dots, (\mathbf{x}^{(n)}, y^{(n)})\}$, where $\mathbf{x}^{(i)} \in \mathbb{N}_0^d$ and $y^{(i)} \in \{0, 1\}$. Here, $\mathbf{x} = [x_1, \dots, x_d]$ and the class conditional distributions, $P(x_i|y)$, are given by independent Poisson distributions. What is the joint distribution $P(\mathbf{x}, y)$?

Solution:

Definition of joint distribution: P(A, B) := P(B)P(A|B).
 In our case:

$$P(\mathbf{x}, y) = P(x_1, \dots, x_d, y) = P(x_2, \dots, x_d, y) P(x_1 | x_2, \dots, x_d, y).$$

Since x_i :s are independent, $P(x_1|x_2,...,x_d,y) = P(x_1|y)$.

Hence,

$$P(\mathbf{x}, y) = P(x_{2}, ..., x_{d}, y)P(x_{1}|y)$$

$$= P(x_{3}, ..., x_{d}, y)P(x_{1}|y)P(x_{2}|y)$$

$$= ... = P(y)P(x_{1}|y)...P(x_{d}|y)$$

$$= P(y)\prod_{i=1}^{d} P(x_{j}|y).$$

▶ Let λ_0 , $\lambda_1 \in \mathbb{R}^d$ be the parameters of the Poisson distributions for y = 0 and y = 1 respectively. Then

$$egin{aligned} P(\mathbf{x},y) &= P(y) \prod_{j=1}^d extsf{Poisson}(\lambda_{y,j}) \ &= P(y) \prod_{j=1}^d rac{e^{-\lambda_{y,j}} \lambda_{y,j}^{x_j}}{x_j!}. \end{aligned}$$

Use MLE to optimize the parameters $p_y := P(Y = y)$ and $\lambda_{y,j}$.

Solution:

- ▶ Define, $n_1 = \sum_{i=1}^n y_i$ and $n_0 = n n_1$. The probability of observing y is $p_y = P(Y = y) = \frac{n_y}{n}$.
- From Question 6, the MLE for λ_{y,j} is the empirical mean of x_j (j denotes dimension, not sample) labeled as y. More precisely,

$$\lambda_{y,j} = \frac{1}{n_y} \sum_{i=1}^n x_j^{(i)} I_{Y_j = y}.$$

New observation, $\mathbf{x} \in \mathcal{X}$, predict $y_{\text{pred}} = \arg \max_{y \in \mathcal{Y}} P(y|X = \mathbf{x})$. Find the hyperplane that determines the label prediction.

Solution:

- Decision boundary: $P(y = 0 | X = \mathbf{x}) = P(y = 1 | X = \mathbf{x})$.
- Joint distribution: $P(y, X = \mathbf{x}) = P(\mathbf{x})P(y|X = \mathbf{x})$.

Hence

$$P(y = 0|X = \mathbf{x}) = P(y = 1|X = \mathbf{x})$$
$$\iff P(y = 0, X = \mathbf{x}) = P(y = 1, X = \mathbf{x}).$$
(1)

From Question 7:
$$P(y, X = \mathbf{x}) = p_y \prod_{j=1}^d \frac{e^{-\lambda_{y,j}} \lambda_{y,j}^{x_j}}{x_j!}$$

$$(1) \Longleftrightarrow p_0 \prod_{j=1}^d \frac{e^{-\lambda_{0,j}} \lambda_{0,j}^{x_j}}{x_j!} = p_1 \prod_{j=1}^d \frac{e^{-\lambda_{1,j}} \lambda_{1,j}^{x_j}}{x_j!}$$

▶ We cancel out *x_j*! and do log:

$$p_0 \prod_{j=1}^d e^{-\lambda_{0,j}} \lambda_{0,j}^{x_j} = p_1 \prod_{j=1}^d e^{-\lambda_{1,j}} \lambda_{1,j}^{x_j}$$
$$\iff \log p_0 + \sum_{j=1}^d \log \left(e^{-\lambda_{0,j}} \lambda_{0,j}^{x_j} \right) = \log p_1 \sum_{j=1}^d \log \left(e^{-\lambda_{1,j}} \lambda_{1,j}^{x_j} \right)$$
$$\iff \log p_0 + \sum_{j=1}^d (x_j \log \lambda_{0,j} - \lambda_{0,j}) = \log p_1 + \sum_{j=1}^d (x_j \log \lambda_{1,j} - \lambda_{1,j})$$
$$\iff \log \frac{p_1}{p_0} + \sum_{j=1}^d (x_j \log \frac{\lambda_{1,j}}{\lambda_{0,j}} + \lambda_{0,j} - \lambda_{1,j}) = 0.$$

• Define $a_j := \log \frac{\lambda_{1,j}}{\lambda_{0,j}}, \ b := -\log \frac{p_1}{p_0} + \sum_{j=1}^d (\lambda_{1,j} - \lambda_{0,j})$, then $\iff \mathbf{a}^T \mathbf{x} = b.$ Inequality (arbitrary assignment on the boundary):

$$y_{\text{pred}} = 1 \iff P(y = 0 | X = \mathbf{x}) \le P(y = 1 | X = \mathbf{x})$$
$$\iff \mathbf{a}^T \mathbf{x} \ge b,$$
$$y_{\text{pred}} = 0 \iff \mathbf{a}^T \mathbf{x} < b.$$

To sumarize: $y_{\text{pred}} = [\mathbf{a}^T \mathbf{x} \ge b].$

One can define a cost function $c : \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}$, such that $c(y_{\text{pred}}, y_{\text{true}})$ is the cost of predicting y_{pred} given the true label is y_{true} . What is the Bayes optimal decision rule for c wrt a distribution P(X, Y).

Solution: According to Bayesian Decision Theory, the best action (from A) to take is the one that minimizes the cost

$$a^* = \arg\min_{a \in \mathcal{A}} \mathbb{E}_Y[c(a, Y)|X].$$

In our case, $\mathcal{A}=\mathcal{Y}$ (the decision corresponds to picking a label), so we conclude that

$$y^* = \arg\min_{y \in \mathcal{Y}} \mathbb{E}_{Y}[c(y, Y)|X].$$

Note: Answer (c) is correct, not (a) as previously stated.

Posterior probabilities for multiclass logistic regression $P(y = k | X = \mathbf{x}) = \frac{\exp(\mathbf{a}_k^T \mathbf{x})}{\sum_i \exp(\mathbf{a}_i^T \mathbf{x})}.$ The cross entropy error reads

$$E(\mathbf{a}_1,\ldots,\mathbf{a}_K)=-\sum_{n=1}^N\sum_{k=1}^Kt_{nk}\log P(y=k|X=\mathbf{x}_n),$$

where $t_{nk} := \delta_{\text{label of } \mathbf{x}_{n,k}}$. Compute $\nabla_{\mathbf{a}_j} E$.

Solution: First, define $y_{kn} := P(y = k | X = \mathbf{x}_n)$. Note that

$$\nabla_{\mathbf{a}_j} E = -\sum_n \sum_k t_{nk} \frac{\nabla_{\mathbf{a}_j} y_{kn}}{y_{kn}}.$$

So we need to expand $\nabla_{\mathbf{a}_j} y_{kn}$. Two cases: (a) j = k, (b) $j \neq k$.

Recall:
$$y_{kn} = \frac{\exp(\mathbf{a}_k^T \mathbf{x}_n)}{\sum_i \exp(\mathbf{a}_i^T \mathbf{x}_n)}$$
, $\mathbf{a}_j = [a_{j1}, \dots, a_{jd}]$, $\mathbf{x}_n = [x_{n1}, \dots, x_{nd}]$.
(a) $j = k$

$$\frac{\partial y_{kn}}{\partial a_{j\ell}} = \frac{x_{n\ell} \exp(\mathbf{a}_k^T \mathbf{x}_n) \sum_i \exp(\mathbf{a}_i^T \mathbf{x}_n) - x_{n\ell} \exp(\mathbf{a}_k^T \mathbf{x}_n) \exp(\mathbf{a}_j^T \mathbf{x}_n)}{\left(\sum_i \exp(\mathbf{a}_i^T \mathbf{x}_n)\right)^2}$$
$$= x_{n\ell} y_{kn} (1 - y_{jn}).$$

• (b)
$$j \neq k$$
, the first term disappears,

$$\frac{\partial y_{kn}}{\partial a_{j\ell}} = -\frac{x_{n\ell} \exp(\mathbf{a}_k^T \mathbf{x}_n) \exp(\mathbf{a}_j^T \mathbf{x}_n)}{\left(\sum_i \exp(\mathbf{a}_i^T \mathbf{x}_n)\right)^2} = -x_{n\ell} y_{kn} y_{jn}.$$

Altogether (vector-wise):

$$\nabla_{\mathbf{a}_j} y_{kn} = \mathbf{x}_n y_{kn} (\delta_{jk} - y_{jn}).$$

Then

$$\nabla_{\mathbf{a}_{j}} E = -\sum_{n} \sum_{k} t_{nk} \frac{\nabla_{\mathbf{a}_{j}} y_{kn}}{y_{kn}}$$

$$= -\sum_{n} \sum_{k} t_{nk} \frac{\mathbf{x}_{n} y_{kn} (\delta_{jk} - y_{jn})}{y_{kn}}$$

$$= -\sum_{n} \mathbf{x}_{n} \left(\sum_{k} t_{nk} \delta_{jk} - y_{jn} \sum_{k} t_{nk} \right)$$

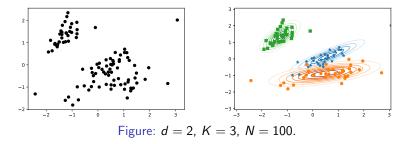
$$= \sum_{n} \mathbf{x}_{n} (y_{jn} - t_{nj})$$

$$= \sum_{n} \mathbf{x}_{n} (P(y = j | X = \mathbf{x}_{n}) - t_{nj}).$$

Gaussian mixture models

GMM: Tailored to fit multimodal distributions.

- d dimensions
- N observations
- K mixture components, each normal but with different parameters (mean, covariance matrix)



Expectation-Maximization (EM)

We assume

$$p(\mathbf{x}|\theta) = \sum_{k=1}^{K} \pi_k \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k), \qquad \pi_k \ge 0, \quad \sum_k \pi_k = 1,$$

where $\theta = (\pi, \mu, \Sigma)$. Let us introduce the latent variable $z \in \{1, \ldots, K\}$ to determine the component from which an observation originates. It's prior and conditional distributions are

$$p(z=k) = \pi_k, \qquad p(\mathbf{x}|z=k) = \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k).$$

EM algorithm:

E step: membership probabilities

$$r_{nk} := p(z_n = k | \mathbf{x}_n) = \frac{\pi_k \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)}$$

M step: Maximize likelihood function over all sample points

$$p(\mathbf{x}_{1:N}|\theta) = \prod_{n=1}^{N} p(\mathbf{x}_n|\theta) = \prod_{n=1}^{N} \sum_{k=1}^{K} \pi_k \mathcal{N}(\mathbf{x}_n|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k).$$

M step

More convenient: maximize the following related loss function instead

$$L(\theta) = \mathbb{E}[p(\mathbf{x}, z | \theta)] = \sum_{n=1}^{N} \sum_{k=1}^{K} r_{nk} \log(\pi_k \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)).$$

Differentiating wrt to $\boldsymbol{\theta}$ and setting to 0, the optimal solution reads

$$\boldsymbol{\mu}_{k} = \frac{\sum_{n=1}^{N} r_{nk} \mathbf{x}_{n}}{\sum_{n=1}^{N} r_{nk}},$$

$$\boldsymbol{\Sigma}_{k} = \frac{\sum_{n=1}^{N} r_{nk} (\mathbf{x}_{n} - \boldsymbol{\mu}_{k}) (\mathbf{x}_{n} - \boldsymbol{\mu}_{k})^{T}}{\sum_{n=1}^{N} r_{nk}},$$

$$\boldsymbol{\pi}_{k} = \frac{\sum_{n=1}^{N} r_{nk}}{\sum_{k=1}^{K} \sum_{n=1}^{N} r_{nk}}.$$

Moreover $N_k = \sum_{n=1}^N r_{nk}$ and $\sum_{k=1}^K N_k = N$.

You are given a data set $D = \{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_N, y_N)\}, \mathbf{x}_i \in \mathbb{R}^d, y_i \in \mathbb{R}, i = 1, \dots, N$. The data points accumulate on *m* different lines, $\mathbf{a}_j^T \mathbf{x}_i = y_i$, for $\mathbf{a}_j \in \mathbb{R}^d$, $j = 1, \dots, m$.

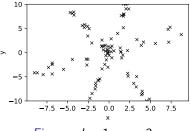


Figure: d = 1, m = 3.

Then

$$p(\mathbf{x}, y|\theta) = \sum_{j=1}^{m} \pi_j \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(\mathbf{a}_j^T \mathbf{x} - y)^2}{2\sigma^2}\right),$$

where $\theta = (\pi_{1:m}, \mathbf{a}_{1:m})$, $\sum \pi_j = 1$, $\pi_j \ge 0$ and $\sigma > 0$ is given and fixed.

- (a) Find the responsibilities in the E-step of Soft EM, $r_{nk}^{(t)} = p(z_n = k | \mathbf{x}_n, y_n, \theta^{(t-1)}).$
- ▶ (b) Write down the class predictions z_n^(t) for (x_n, z_n) in the E-step of Hard EM in terms of r_{nk}^(t).
- (c) Assume that we observe the true labels z₁,..., z_ℓ for the first ℓ datapoints, ℓ < N. How can we modify the E-step of Soft EM to incorporate the additional information?</p>
- (d) Write down the optimization objective for the M-step in Soft EM for π_j^(t) and **a**_j^(t) in the terms of the responsibilities r_{nk}^(t).

(a) Find the responsibilities in the E-step of Soft EM,
$$r_{nk}^{(t)} = p(z_n = k | \mathbf{x}_n, y_n, \theta^{(t-1)}).$$

Solution: Using Bayes' theorem (omitting θ)

$$p(z_n = k | \mathbf{x}_n, y_n) = \frac{p(\mathbf{x}_n, y_n | z_n = k) p(z_n = k)}{\sum_{j=1}^m p(\mathbf{x}_n, y_n | z_n = j) p(z_n = j)}.$$

We have
$$p(z = j) = \pi_j^{(t-1)}$$
, and
 $p(\mathbf{x}, y | z = k) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(\mathbf{a}_k^{(t-1)^T} \mathbf{x} - y)^2}{2\sigma^2}\right)$. Hence

$$r_{nk}^{(t)} = \frac{\pi_k^{(t-1)} \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(\mathbf{a}_k^{(t-1)^T} \mathbf{x}_n - y_n)^2}{2\sigma^2}\right)}{\sum_{j=1}^m \pi_j^{(t-1)} \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(\mathbf{a}_j^{(t-1)^T} \mathbf{x}_n - y_n)^2}{2\sigma^2}\right)}.$$

(b) Write down the class predictions $z_n^{(t)}$ for (\mathbf{x}_n, z_n) in the E-step of Hard EM in terms of $r_{nk}^{(t)}$.

Solution

$$z_n^{(t)} = \arg \max_k r_{nk}.$$

(c) Assume that we observe the true labels z_1, \ldots, z_ℓ for the first ℓ datapoints, $\ell < N$. How can we modify the E-step of Soft EM to incorporate the additional information?

Solution: We change responsibilities of the corresponding point-cluster pairs to 1, and set to 0 otherwise, i.e.

$$r_{nk}^{(t)} = \delta_{z_nk}, \quad \text{for } n \leq \ell, \ \forall k.$$

(d) Write down the optimization objective for the M-step in Soft EM for $\pi_j^{(t)}$ and $\mathbf{a}_j^{(t)}$ in the terms of the responsibilities $r_{nk}^{(t)}$.

Solution: Loss function:

$$L(\theta) = \sum_{n=1}^{N} \sum_{k=1}^{m} r_{nk}^{(t)} \log \left(\pi_k \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(\mathbf{a}_k^T \mathbf{x}_n - y_n)^2}{2\sigma^2}\right) \right).$$

We select

$$\pi_{1:m}^{(t)}, \mathbf{a}_{1:m}^{(t)} = \arg \max_{\pi_{1:m}, \mathbf{a}_{1:m}} L(\theta),$$

such that $\pi_j \ge 0$, $\sum_j \pi_j = 1$.

(e) Derive the explicit update rules for $\pi_j^{(t)}$ and $\mathbf{a}_j^{(t)}$ used in the M-step of Soft EM. Hint: You can assume that the matrix $\sum_{n=1}^{N} r_{nk}^{(t)} \mathbf{x}_n \mathbf{x}_n^T$ is invertible for all k = 1, ..., m.

Solution: First, denote
$$y_{kn} := \pi_k \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(\mathbf{a}_k^T \mathbf{x}_n - y_n)^2}{2\sigma^2}\right)$$
. Then differentiate $L(\theta) = \sum_{n=1}^N \sum_{k=1}^m r_{nk}^{(t)} \log(y_{kn})$ wrt \mathbf{a}_j :

$$\frac{\partial L}{\partial a_{j\ell}} = \sum_{n} r_{nj}^{(t)} \frac{\partial_{a_{j\ell}} y_{jn}}{y_{jn}} = \sum_{n} r_{nj}^{(t)} \frac{-y_{jn} \left(\frac{1}{\sigma^2}\right) (\mathbf{a}_j^T \mathbf{x}_n - y_n) x_{n\ell}}{y_{jn}}.$$

We want $\frac{\partial L}{\partial a_{j\ell}} = 0$ hence (vector-wise)

$$\sum_{n} r_{nj}^{(t)} (\mathbf{a}_{j}^{T} \mathbf{x}_{n} - y_{n}) \mathbf{x}_{n}^{T} = 0$$
$$\iff \mathbf{a}_{j}^{T} \sum_{n} r_{nj}^{(t)} \mathbf{x}_{n} \mathbf{x}_{n}^{T} = \sum_{n} r_{nj}^{(t)} y_{n} \mathbf{x}_{n}^{T}.$$

Since $\sum_{n=1}^{N} r_{nk}^{(t)} \mathbf{x}_n \mathbf{x}_n^T$ is invertible, we can write

$$\mathbf{a}_{j}^{\mathsf{T}} = \left(\sum_{n} r_{nj}^{(t)} y_{n} \mathbf{x}_{n}^{\mathsf{T}}\right) \left(\sum_{n} r_{nj}^{(t)} \mathbf{x}_{n} \mathbf{x}_{n}^{\mathsf{T}}\right)^{-1}$$

Similarly, we want to differentiate L wrt to π_j to obtain the extrema, however, we must not forget the constraint $\sum_k \pi_k = 1!$ To incorporate it, we will use the Lagrange multipliers. More precisely, we want to maximize

$$\widetilde{L}(heta) = L(heta) + \lambda \left(\sum_k \pi_k - 1\right).$$

Then differentiation wrt both λ and π_j gives

$$\frac{\partial \widetilde{L}}{\partial \lambda} = \sum_{k} \pi_{k} - 1 \qquad =^{!} 0,$$
$$\frac{\partial \widetilde{L}}{\partial \pi_{j}} = \sum_{n} r_{nj}^{(t)} \frac{1}{\pi_{j}} + \lambda \qquad =^{!} 0.$$

Let us define $d_j := \sum_n r_{nj}$. We obtained the following equations

$$\lambda = -rac{d_j}{\pi_j}, \qquad \sum_j \pi_j = 1.$$

Combining these, we conclude that

$$\pi_j = -\frac{d_j}{\lambda} \Rightarrow 1 = \sum_j \pi_j = -\sum_j \frac{d_j}{\lambda} \Rightarrow \lambda = -\sum_j d_j,$$

and finally

$$\pi_j = \frac{d_j}{\sum_j d_j}.$$

Note that indeed $\pi_j \ge 0$ and $\sum_j \pi_j = 1$.

Exercise 2

Suppose the lifetime of lightbulbs follows exponential distribution with unknown mean θ . In an experiment with N bulbs, the exact lifetimes Y_1, \ldots, Y_N are recorded. In another experiment with M bulbs, we enter the lab at time t > 0, and register which of the lightbulbs are still burning (indicator $E_i = 1$), and which have expired ($E_i = 0$). What is the MLE of θ ?

Solution: Let X_1, \ldots, X_M be the (unobserved) lifetimes associated with the second experiment, and $Z = \sum_{i=1}^{M} E_i$ the number of lightbulbs in the second experiment that are still alive at time t. Thus, the observed data from both the experiments combined is

$$\mathcal{Y} = (Y_1, \ldots, Y_N, E_1, \ldots, E_M),$$

and the unobserved data is

$$\mathcal{X} = (X_1, \ldots, X_M).$$

Exercise 2

Exponential distribution $p(Y|\theta) = \frac{1}{\theta} \exp(-Y/\theta)$. The log-likelihood is

$$\begin{split} L(\theta) &= \log \left(\prod_{j=1}^{N} p(Y_j|\theta) \prod_{j=1}^{M} p(X_j|\theta) \right) \\ &= -N \log(\theta) - \frac{1}{\theta} \sum_{j=1}^{N} Y_j - M \log(\theta) - \frac{1}{\theta} \sum_{j=1}^{M} X_j. \end{split}$$

But X is not observed. We replace it with its expected value $\mathbb{E}[X_i|\mathcal{Y}]$,

$$\mathbb{E}[X_i|\mathcal{Y}] = \mathbb{E}[X_i|E_i] = \begin{cases} t+\theta, & \text{for } E_i = 1, \\ \theta - tp, & \text{for } E_i = 0, \end{cases}$$

where $p := \frac{\exp(-t/\theta)}{1-\exp(-t/\theta)}$.

Exercise 2

Then using the current numerical parameter $\theta^{(i-1)}$

$$egin{aligned} \widetilde{L}^{(i)}(heta) &= -\log(heta)(N+M) - rac{1}{ heta}\sum_{j=1}^N Y_j - rac{1}{ heta}\sum_{j=1}^M \mathbb{E}[X_j|E_j] \ &= -\log(heta)(N+M) - rac{1}{ heta}N\overline{Y} \ &- rac{1}{ heta}\left(Z(t+ heta^{(i-1)}) + (M-Z)(heta^{(i-1)}-tp^{(i-1)})
ight) \end{aligned}$$

The solution to $(\widetilde{L}^{(i)}(\theta))' = 0$ gives the M-step

$$\theta^{(i)} = \frac{N\overline{Y} + Z(t + \theta^{(i-1)}) + (M - Z)(\theta^{(i-1)} - tp^{(i-1)})}{M + N}.$$

References

- Lecture slides & videos
- Bernard Flury and Alice Zoppe. Exercises in EM.
- Victor Lavrenko. EM algorithm: how it works.